

STOCHASTIC MODELING OF ENVIRONMENTAL TIME SERIES

Richard W. Katz

LECTURE 1

(1) Environmental Motivation

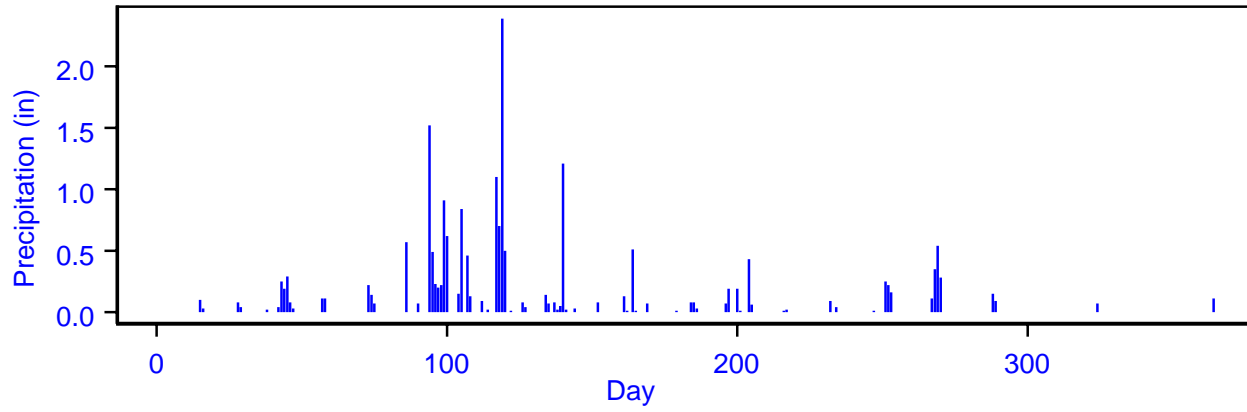
(2) Probabilistic Background

(3) Statistical Background

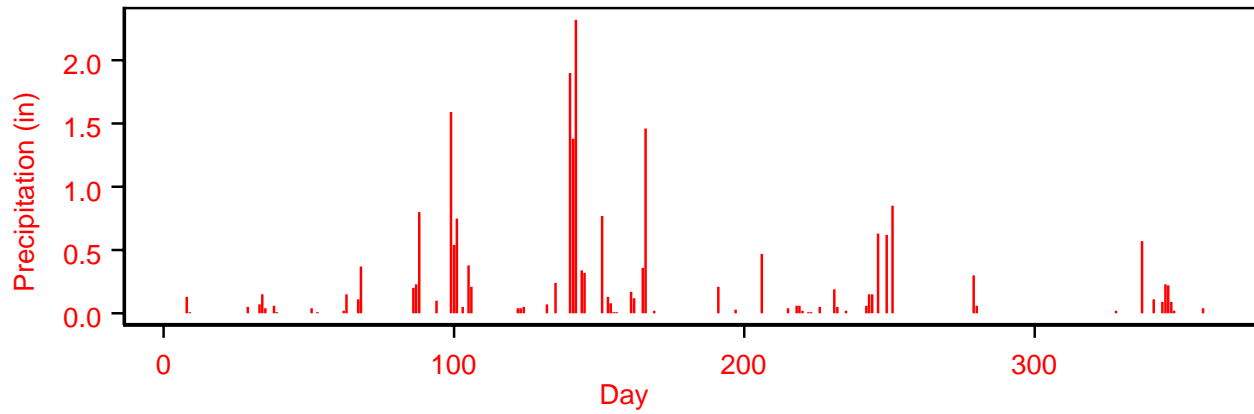
(1) Environmental Motivation

- **Example**
 - **Time series of daily precipitation amount at single location (Fort Collins, CO, USA: 1900 – 1999)**
- **Statistical Characteristics of Environmental Time Series**
- **Scientific Research Questions**

Fort Collins, CO, USA daily precipitation amount: Year 1900



Fort Collins, CO, USA daily precipitation amount: Year 1901



Statistical Characteristics

- Intermittency
- Skewness
- Extremes (heavy tail?)
- Temporal dependence
- Seasonality
- Spatial dependence (not shown)
- Trend?

Scientific Research Questions

Overdispersion

-- Stochastic models for daily precipitation tend to underestimate variance of monthly, seasonal, or annual total precipitation

Explanations

- High Frequency Variations

- Inadequate stochastic model for daily precipitation?

- Low Frequency Variations

- “Potential predictability” or climate change?

(2) Probabilistic Background

Preliminaries

-- To be used in statistical modeling of overdispersion phenomenon

- Scaling/Aggregation**
- Conditional Moments**
- Effects of Intermittency**

Scaling/Aggregation

- **Stationary stochastic process** $\{X_t: t = 1, 2, \dots\}$

- **Moments**

$$\mu = \mathbf{E}(X_t), \quad \sigma^2 = \mathbf{Var}(X_t), \quad \rho_l = \mathbf{Corr}(X_t, X_{t+l}), \quad l = 1, 2, \dots$$

- **Sum** $S_T = X_1 + X_2 + \dots + X_T$

- **Variance**

$$(1/T) \mathbf{Var}(S_T) \rightarrow \sigma^2 [1 + 2(\rho_1 + \rho_2 + \dots)] \equiv (\sigma^*)^2 \text{ as } T \rightarrow \infty$$

- **Distribution** $(S_T - T\mu) / (\sigma^* T^{1/2}) \rightarrow N(0, 1)$ (in distribution)

- **Example: First-order autoregressive [AR(1)] process**

$$X_{t+1} - \mu = \varphi(X_t - \mu) + \varepsilon_t, \quad t = 1, 2, \dots$$

$$\mathbf{E}(\varepsilon_t) = \mathbf{0}, \quad \mathbf{E}(\varepsilon_t \varepsilon_{t+l}) = \mathbf{0}, \quad l = 1, 2, \dots$$

Here $\mu = \mathbf{E}(X_t)$, $\sigma^2 = \mathbf{Var}(X_t)$, $\varphi = \mathbf{Corr}(X_t, X_{t+1})$

– Variance of sum S_T

$$(1/T) \mathbf{Var}(S_T) \rightarrow (\sigma^*)^2 = \sigma^2 [(1 + \varphi)/(1 - \varphi)] \text{ as } T \rightarrow \infty$$

Central Limit Theorem holds with this normalizing constant σ^*

- **Example: Two-state, first-order Markov chain**

$$\{J_t: t = 1, 2, \dots\}, \quad J_t = 0, 1$$

Transition probabilities:

$$P_{jk} = \Pr\{J_{t+1} = k \mid J_t = j\}; \quad j, k = 0, 1$$

$$\pi = \Pr\{J_t = 1\} = P_{01} / (P_{10} + P_{01}), \quad d = \text{Corr}(J_t, J_{t+1}) = P_{11} - P_{01}$$

Sum:
$$N(T) = J_1 + J_2 + \dots + J_T$$

Variance:

$$(1/T) \text{Var}[N(T)] \rightarrow (\sigma^*)^2 = \pi(1 - \pi) [(1 + d)/(1 - d)] \quad \text{as } T \rightarrow \infty$$

Central Limit Theorem holds with this normalizing constant σ^*

Conditional Moments

- **Expected Value**

$$E(X) = E[E(X|Y)]$$

- **Variance**

$$\text{Var}(X) = E[\text{Var}(X|Y)] + \text{Var}[E(X|Y)]$$

- **Covariance**

$$\text{Cov}(X, Y) = E[\text{Cov}(X, Y|Z)] + \text{Cov}[E(X|Z), E(Y|Z)]$$

Effects of Intermittency

$\{N(t): t = 1, 2, \dots\}$ number of events in time interval $[0, t]$ (corresponding to point process)

$\{X_t: t = 1, 2, \dots\}$ independent and identically distributed [$\mu = E(X_t)$, $\sigma^2 = \text{Var}(X_t)$]

$\{X_t\}$ independent of $\{N(t)\}$

• **Random sum** $S_{N(T)} = X_1 + X_2 + \dots + X_{N(T)}$

Mean: $E[S_{N(T)}] = E[N(T)] \mu$

Variance: $\text{Var}[S_{N(T)}] = E[N(T)] \sigma^2 + \text{Var}[N(T)] \mu^2$

Central Limit Theorem: Still holds for $S_{N(T)}$

- **Extremes**

- **Ordinary maximum** $M_T = \max\{X_1, X_2, \dots, X_T\}$

Extreme value theorem: M_T , suitably normalized, has asymptotically **Generalized Extreme Value (GEV)** distribution function

$$G(x) = \exp\left(-\left\{1 + \xi \left[\frac{x - \mu}{\sigma}\right]\right\}^{-1/\xi}\right), \quad 1 + \xi \left[\frac{x - \mu}{\sigma}\right] > 0$$

- **Maximum with random indices**

$$M_{N(T)} = \max\{X_1, X_2, \dots, X_{N(T)}\}$$

Extreme value theorem still holds for $M_{N(T)}$ if

$$(1/T) N(T) \rightarrow \pi \text{ as } T \rightarrow \infty \text{ (in probability)}$$

But now limiting distribution is $[G(x)]^\pi$ (i.e., GEV with adjusted parameters)

(3) Statistical Background

Mixtures:

-- Chance mechanism for overdispersion

- **Mixture of Distributions**
- **Dependence Induced by Mixtures**

Mixture of Distributions

- Finite mixture (two-component case):

$$\Pr\{X \leq x\} = \Pr\{X \leq x \mid I = 0\} \Pr\{I = 0\} + \Pr\{X \leq x \mid I = 1\} \Pr\{I = 1\}$$

I two-state random variable (generally only observe *X*, not *I*)

-- Notation $F(x) = \Pr\{X \leq x\}$, $F_i(x) = \Pr\{X \leq x \mid I = i\}$, $w = \Pr\{I = 1\}$,

$$\mu_i = E(X \mid I = i), \quad \sigma_i^2 = \text{Var}(X \mid I = i), \quad i = 0, 1$$

-- Moments $E(X) = (1 - w)\mu_0 + w\mu_1$

$$\text{Var}(X) = (1 - w)\sigma_0^2 + w\sigma_1^2 + w(1 - w)(\mu_1 - \mu_0)^2$$

- **Example: Mixture of two normal distributions**

Conditional densities:

$$f_i(x) = [(2\pi)^{1/2} \sigma_i]^{-1} \exp(-1/2[(x - \mu_i)/\sigma_i]^2), \quad i = 0, 1$$

-- Unimodal or bimodal?

Only bimodal if difference between μ_0 and μ_1 large enough relative to σ_0 and σ_1

Sufficient condition for unimodal distribution:

$$|\mu_1 - \mu_0| \leq 2 \min(\sigma_0, \sigma_1)$$

- **Example: Mixture of two exponential distributions**

$$F_i(x) = 1 - (1/\sigma_i) \exp[-(x/\sigma_i)], \quad x > 0, \quad i = 0, 1$$

- Longer tail than single exponential (*not* memoryless)

$$\Pr\{X \leq u + x \mid X > u, I = i\} = \Pr\{X \leq x \mid I = i\}, \quad i = 0, 1$$

But

$$\Pr\{X \leq u + x \mid X > u\} \neq \Pr\{X \leq x\}$$

- Used to fit precipitation “intensity”

Conditional distribution of precipitation amount given occurrence:

$$\Pr\{X \leq x \mid X > 0\}$$

- **Example: Infinite-dimensional mixture of exponentials**

- Let X have conditional exponential distribution

$$\Pr\{X \leq x \mid \sigma\} = 1 - (1/\sigma) \exp[-(x/\sigma)],$$

where $Y = 1/\sigma$ has gamma distribution

$$\Pr\{Y \leq y\} = [\beta\Gamma(\alpha)]^{-1} (y/\beta)^{\alpha-1} \exp[-(y/\beta)], \quad y > 0$$

Then unconditional distribution of X is Pareto

$$\Pr\{X \leq x\} = 1 - (1 + \beta x)^{-\alpha}$$

- Chance mechanism by which heavy tail obtained from light tail

Dependence Induced by Mixtures

- **Example: Induced “spatial” dependence**

Let X & Y both have mixture distributions given same two-state conditioning variable I

Conditional means: $\mu_X(i) = E(X | I = i)$, $\mu_Y(i) = E(Y | I = i)$, $i = 0, 1$

Conditional variances: $[\sigma_X(i)]^2 = \text{Var}(X | I = i)$, $[\sigma_Y(i)]^2 = \text{Var}(Y | I = i)$

Assume X & Y conditionally independent given I [so $\text{Cov}(X, Y|I) = 0$]

-- Unconditional covariance

$$\text{Cov}(X, Y) = w(1 - w)[\mu_X(1) - \mu_X(0)][\mu_Y(1) - \mu_Y(0)]$$

- **Example: Hidden Markov model**

$\{X_t: t = 1, 2, \dots\}$ has mixture distribution given J_t (two-state variable with conditional means μ_0 & μ_1 , standard deviations σ_0 & σ_1)

$\{J_t: t = 1, 2, \dots\}$ first-order Markov chain (with parameters π & d)

Assume $\{X_t\}$ conditionally independent given $\{J_t\}$

– Unconditional autocorrelation function of $\{X_t\}$

$$\text{Corr}(X_t, X_{t+l}) = a \text{Corr}(J_t, J_{t+l}) = a d^l, \quad l = 1, 2, \dots$$

Where

$$a = [\pi(1 - \pi)(\mu_1 - \mu_0)^2] / \text{Var}(X_t),$$

$$\text{Var}(X_t) = (1 - \pi)\sigma_0^2 + \pi\sigma_1^2 + \pi(1 - \pi)(\mu_1 - \mu_0)^2$$

- **Example: AR(1) process with shifting mean**

$\{X_t: t = 1, 2, \dots\}$ conditional AR(1) process given $\{I_t: t = 1, 2, \dots\}$

$$\mu_i = \mathbf{E}(X_t | I_t = i), \quad i = 0, 1$$

Assume $\sigma_i^2 = \mathbf{Var}(X_t | I_t = i) = \sigma^2, \quad i = 0, 1,$

$$\varphi_{ij} = \mathbf{Corr}(X_t, X_{t+1} | I_t = i, I_{t+1} = j) = \varphi, \quad i, j = 0, 1$$

$\{I_t\}$ independent & identically distributed ($w = \mathbf{Pr}\{I = 1\}$)

-- **Autocorrelation function of $\{X_t\}$**

$$\mathbf{Corr}(X_t, X_{t+l}) = a \varphi^l, \quad l = 1, 2, \dots$$

where $a = \sigma^2 / \mathbf{Var}(X_t), \quad \mathbf{Var}(X_t) = \sigma^2 + w(1 - w)(\mu_1 - \mu_0)^2$

Derivation of autocorrelation function:

Because $\text{Cov}[\mathbf{E}(X_t | I_t, I_{t+l}), \mathbf{E}(X_{t+l} | I_t, I_{t+l})] = 0,$

$$\text{Cov}(X_t, X_{t+l}) = \mathbf{E}[\text{Cov}(X_t, X_{t+l} | I_t, I_{t+l})]$$

So $\text{Corr}(X_t, X_{t+l}) = \mathbf{E}[\text{Cov}(X_t, X_{t+l} | I_t, I_{t+l})] / \text{Var}(X_t)$

$$= \sigma^2 \varphi^l / \text{Var}(X_t)$$

$$= \{\sigma^2 / [\sigma^2 + w(1-w)(\mu_1 - \mu_0)^2]\} \varphi^l, \quad l = 1, 2, \dots$$